Specialized hardware and driver enablement

Learn about hardware enablement on OpenShift Container Platform
OpenShift Container Platform 4.10 Specialized hardware and driver enablement

Learn about hardware enablement on OpenShift Container Platform
Abstract

This document provides an overview of hardware enablement in OpenShift Container Platform.
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CHAPTER 1. ABOUT SPECIALIZED HARDWARE AND DRIVER ENABLEMENT

Many applications require specialized hardware or software that depends on kernel modules or drivers. You can use driver containers to load out-of-tree kernel modules on Red Hat Enterprise Linux CoreOS (RHCOS) nodes. To deploy out-of-tree drivers during cluster installation, use the kmods-via-containers framework. To load drivers or kernel modules on an existing OpenShift Container Platform cluster, OpenShift Container Platform offers several tools:

- The Driver Toolkit is a container image that is a part of every OpenShift Container Platform release. It contains the kernel packages and other common dependencies that are needed to build a driver or kernel module. The Driver Toolkit can be used as a base image for driver container image builds on OpenShift Container Platform.

- The Special Resource Operator (SRO) orchestrates the building and management of driver containers to load kernel modules and drivers on an existing OpenShift or Kubernetes cluster.

- The Node Feature Discovery (NFD) Operator adds node labels for CPU capabilities, kernel version, PCIe device vendor IDs, and more.
CHAPTER 2. DRIVER TOOLKIT

Learn about the Driver Toolkit and how you can use it as a base image for driver containers for enabling special software and hardware devices on Kubernetes.

IMPORTANT

The Driver Toolkit is a Technology Preview feature only. Technology Preview features are not supported with Red Hat production service level agreements (SLAs) and might not be functionally complete. Red Hat does not recommend using them in production. These features provide early access to upcoming product features, enabling customers to test functionality and provide feedback during the development process.

For more information about the support scope of Red Hat Technology Preview features, see https://access.redhat.com/support/offerings/techpreview/.

2.1. ABOUT THE DRIVER TOOLKIT

Background

The Driver Toolkit is a container image in the OpenShift Container Platform payload used as a base image on which you can build driver containers. The Driver Toolkit image contains the kernel packages commonly required as dependencies to build or install kernel modules, as well as a few tools needed in driver containers. The version of these packages will match the kernel version running on the Red Hat Enterprise Linux CoreOS (RHCOS) nodes in the corresponding OpenShift Container Platform release.

Driver containers are container images used for building and deploying out-of-tree kernel modules and drivers on container operating systems like RHCOS. Kernel modules and drivers are software libraries running with a high level of privilege in the operating system kernel. They extend the kernel functionalities or provide the hardware-specific code required to control new devices. Examples include hardware devices like Field Programmable Gate Arrays (FPGA) or GPUs, and software-defined storage (SDS) solutions, such as Lustre parallel file systems, which require kernel modules on client machines. Driver containers are the first layer of the software stack used to enable these technologies on Kubernetes.

The list of kernel packages in the Driver Toolkit includes the following and their dependencies:

- kernel-core
- kernel-devel
- kernel-headers
- kernel-modules
- kernel-modules-extra

In addition, the Driver Toolkit also includes the corresponding real-time kernel packages:

- kernel-rt-core
- kernel-rt-devel
- kernel-rt-modules
- kernel-rt-modules-extra
The Driver Toolkit also has several tools which are commonly needed to build and install kernel modules, including:

- elfutils-libelf-devel
- kmod
- binutils-kabi-dw
- kernel-abi-whitelists
- dependencies for the above

Purpose
Prior to the Driver Toolkit’s existence, you could install kernel packages in a pod or build config on OpenShift Container Platform using entitled builds or by installing from the kernel RPMs in the hosts machine-os-content. The Driver Toolkit simplifies the process by removing the entitlement step, and avoids the privileged operation of accessing the machine-os-content in a pod. The Driver Toolkit can also be used by partners who have access to pre-released OpenShift Container Platform versions to prebuild driver-containers for their hardware devices for future OpenShift Container Platform releases.

The Driver Toolkit is also used by the Special Resource Operator (SRO), which is currently available as a community Operator on OperatorHub. SRO supports out-of-tree and third-party kernel drivers and the support software for the underlying operating system. Users can create recipes for SRO to build and deploy a driver container, as well as support software like a device plug-in, or metrics. Recipes can include a build config to build a driver container based on the Driver Toolkit, or SRO can deploy a prebuilt driver container.

2.2. PULLING THE DRIVER TOOLKIT CONTAINER IMAGE

The driver-toolkit image is available from the Container images section of the Red Hat Ecosystem Catalog and in the OpenShift Container Platform release payload. The image corresponding to the most recent minor release of OpenShift Container Platform will be tagged with the version number in the catalog. The image URL for a specific release can be found using the oc adm CLI command.

2.2.1. Pulling the Driver Toolkit container image from registry.redhat.io

Instructions for pulling the driver-toolkit image from registry.redhat.io with podman or in OpenShift Container Platform can be found on the Red Hat Ecosystem Catalog. The driver-toolkit image for the latest minor release will be tagged with the minor release version on registry.redhat.io for example registry.redhat.io/openshift4/driver-toolkit-rhel8:v4.10.

2.2.2. Finding the Driver Toolkit image URL in the payload

Prerequisites

- You obtained the image pull secret from the Red Hat OpenShift Cluster Manager.
- You installed the OpenShift CLI (oc).

Procedure

1. The image URL of the driver-toolkit corresponding to a certain release can be extracted from the release image using the oc adm command:
2. This image can be pulled using a valid pull secret, such as the pull secret required to install OpenShift Container Platform.

2.3. USING THE DRIVER TOOLKIT

As an example, the Driver Toolkit can be used as the base image for building a very simple kernel module called simple-kmod.

NOTE

The Driver Toolkit contains the necessary dependencies, openssl, mokutil, and keyutils, needed to sign a kernel module. However, in this example, the simple-kmod kernel module is not signed and therefore cannot be loaded on systems with Secure Boot enabled.

2.3.1. Build and run the simple-kmod driver container on a cluster

Prerequisites

- You have a running OpenShift Container Platform cluster.
- You set the Image Registry Operator state to Managed for your cluster.
- You installed the OpenShift CLI (oc).
- You are logged into the OpenShift CLI as a user with cluster-admin privileges.

Procedure

Create a namespace. For example:

$ oc new-project simple-kmod-demo

1. The YAML defines an ImageStream for storing the simple-kmod driver container image, and a BuildConfig for building the container. Save this YAML as 0000-buildconfig.yaml.template.

```
apiVersion: image.openshift.io/v1
kind: ImageStream
metadata:
  labels:
    app: simple-kmod-driver-container
    name: simple-kmod-driver-container
    namespace: simple-kmod-demo
```
spec: {}
---
apiVersion: build.openshift.io/v1
kind: BuildConfig
metadata:
  labels:
    app: simple-kmod-driver-build
  name: simple-kmod-driver-build
  namespace: simple-kmod-demo
spec:
  nodeSelector:
    node-role.kubernetes.io/worker: ""
  runPolicy: "Serial"
  triggers:
    - type: "ConfigChange"
    - type: "ImageChange"
  source:
    git:
      ref: "master"
      uri: "https://github.com/openshift-psap/simple-kmod.git"
    type: Git
dockerfile: |
      FROM DRIVER_TOOLKIT_IMAGE
      WORKDIR /build/
      # Expecting kmod software version as an input to the build
      ARG KMODVER
      # Grab the software from upstream
      RUN git clone https://github.com/openshift-psap/simple-kmod.git
      WORKDIR simple-kmod
      # Build and install the module
      RUN make all KVER=$(rpm -qf "%%{VERSION}-%{RELEASE}.%{ARCH}" kernel-core) KMODVER=${KMODVER} \   && make install KVER=$(rpm -qf "%%{VERSION}-%{RELEASE}.%{ARCH}" kernel-core) KMODVER=${KMODVER} \      # Add the helper tools
      WORKDIR /root/kvc-simple-kmod
      ADD Makefile .
      ADD simple-kmod-lib.sh .
      ADD simple-kmod-wrapper.sh .
      ADD simple-kmod.conf .
      RUN mkdir -p /usr/lib/kvc/ \   && mkdir -p /etc/kvc/ \      && make install
      RUN systemctl enable kmods-via-containers@simple-kmod
strategy:
dockerStrategy:
  buildArgs:
    - name: KMODVER
      value: DEMO
output:
2. Substitute the correct driver toolkit image for the OpenShift Container Platform version you are running in place of “DRIVER_TOOLKIT_IMAGE” with the following commands.

   ```bash
   $ OCP_VERSION=$(oc get clusterversion/version -ojsonpath={.status.desired.version})
   $ DRIVER_TOOLKIT_IMAGE=$(oc adm release info $OCP_VERSION --image-for=driver-toolkit)
   $ sed "s#DRIVER_TOOLKIT_IMAGE#${DRIVER_TOOLKIT_IMAGE}#" 0000-buildconfig.yaml.template > 0000-buildconfig.yaml
   ```

3. Create the image stream and build config with

   ```bash
   $ oc create -f 0000-buildconfig.yaml
   ```

4. After the builder pod completes successfully, deploy the driver container image as a **DaemonSet**.

   a. The driver container must run with the privileged security context in order to load the kernel modules on the host. The following YAML file contains the RBAC rules and the **DaemonSet** for running the driver container. Save this YAML as `1000-drivercontainer.yaml`.

   ```yaml
   apiVersion: v1
   kind: ServiceAccount
   metadata:
     name: simple-kmod-driver-container
   ---
   apiVersion: rbac.authorization.k8s.io/v1
   kind: Role
   metadata:
     name: simple-kmod-driver-container
   rules:
     - apiGroups:
       - security.openshift.io
       resources:
       - securitycontextconstraints
       verbs:
       - use
       resourceNames:
       - privileged
   ---
   apiVersion: rbac.authorization.k8s.io/v1
   kind: RoleBinding
   metadata:
     name: simple-kmod-driver-container
   roleRef:
     apiGroup: rbac.authorization.k8s.io
     kind: Role
     name: simple-kmod-driver-container
   subjects:
   ```
Create the RBAC rules and daemon set:

```yaml
- kind: ServiceAccount
  name: simple-kmod-driver-container
  userNames:
- system.serviceaccount:simple-kmod-demo:simple-kmod-driver-container

---
apiVersion: apps/v1
kind: DaemonSet
metadata:
  name: simple-kmod-driver-container
spec:
  selector:
    matchLabels:
      app: simple-kmod-driver-container
  template:
    metadata:
      labels:
        app: simple-kmod-driver-container
    spec:
      serviceAccount: simple-kmod-driver-container
      serviceAccountName: simple-kmod-driver-container
      containers:
        - image: image-registry.openshift-image-registry.svc:5000/simple-kmod-demo/simple-kmod-driver-container:demo
          name: simple-kmod-driver-container
          imagePullPolicy: Always
          command: ["/sbin/init"]
          lifecycle:
            preStop:
              exec:
                command: ["/bin/sh", "-c", "systemctl stop kmods-via-containers@simple-kmod"]
          securityContext:
            privileged: true
      nodeSelector:
        node-role.kubernetes.io/worker: ""

$ oc create -f 1000-drivercontainer.yaml
```

5. After the pods are running on the worker nodes, verify that the `simple_kmod` kernel module is loaded successfully on the host machines with `lsmod`.

a. Verify that the pods are running:

```
$ oc get pod -n simple-kmod-demo
```

**Example output**

<table>
<thead>
<tr>
<th>NAME</th>
<th>READY</th>
<th>STATUS</th>
<th>RESTARTS</th>
<th>AGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple-kmod-driver-build-1-build</td>
<td>0/1</td>
<td>Completed</td>
<td>0</td>
<td>6m</td>
</tr>
<tr>
<td>simple-kmod-driver-container-b22fd</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>40s</td>
</tr>
<tr>
<td>simple-kmod-driver-container-jz9vn</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>40s</td>
</tr>
<tr>
<td>simple-kmod-driver-container-p45cc</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>40s</td>
</tr>
</tbody>
</table>

b. Execute the `lsmod` command in the driver container pod:
$ oc exec -it pod/simple-kmod-driver-container-p45cc -- lsmod | grep simple

Example output

<table>
<thead>
<tr>
<th>Module</th>
<th>Size</th>
<th>Count</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple_procfs_kmod</td>
<td>16384</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>simple_kmod</td>
<td>16384</td>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

2.4. ADDITIONAL RESOURCES

- For more information about configuring registry storage for your cluster, see Image Registry Operator in OpenShift Container Platform.
CHAPTER 3. SPECIAL RESOURCE OPERATOR

Learn about the Special Resource Operator (SRO) and how you can use it to build and manage driver containers for loading kernel modules and device drivers on nodes in an OpenShift Container Platform cluster.

IMPORTANT

The Special Resource Operator is a Technology Preview feature only. Technology Preview features are not supported with Red Hat production service level agreements (SLAs) and might not be functionally complete. Red Hat does not recommend using them in production. These features provide early access to upcoming product features, enabling customers to test functionality and provide feedback during the development process.

For more information about the support scope of Red Hat Technology Preview features, see https://access.redhat.com/support/offerings/techpreview/.

3.1. ABOUT THE SPECIAL RESOURCE OPERATOR

The Special Resource Operator (SRO) helps you manage the deployment of kernel modules and drivers on an existing OpenShift Container Platform cluster. The SRO can be used for a case as simple as building and loading a single kernel module, or as complex as deploying the driver, device plug-in, and monitoring stack for a hardware accelerator.

For loading kernel modules, the SRO is designed around the use of driver containers. Driver containers are increasingly being used in cloud-native environments, especially when run on pure container operating systems, to deliver hardware drivers to the host. Driver containers extend the kernel stack beyond the out-of-the-box software and hardware features of a specific kernel. Driver containers work on various container-capable Linux distributions. With driver containers, the host operating system stays clean and there is no clash between different library versions or binaries on the host.

3.2. INSTALLING THE SPECIAL RESOURCE OPERATOR

As a cluster administrator, you can install the Special Resource Operator (SRO) by using the OpenShift CLI or the web console.

3.2.1. Installing the Special Resource Operator by using the CLI

As a cluster administrator, you can install the Special Resource Operator (SRO) by using the OpenShift CLI.

Prerequisites

- You have a running OpenShift Container Platform cluster.
- You installed the OpenShift CLI (oc).
- You are logged into the OpenShift CLI as a user with `cluster-admin` privileges.
- You installed the Node Feature Discovery (NFD) Operator.

Procedure
1. Create a namespace for the Special Resource Operator:
   a. Create the following **Namespace** custom resource (CR) that defines the `openshift-special-resource-operator` namespace, and then save the YAML in the `sro-namespace.yaml` file:

   ```yaml
   apiVersion: v1
   kind: Namespace
   metadata:
     name: openshift-special-resource-operator
   ```

   b. Create the namespace by running the following command:

   ```bash
   $ oc create -f sro-namespace.yaml
   ```

2. Install the SRO in the namespace you created in the previous step:
   a. Create the following **OperatorGroup** CR and save the YAML in the `sro-operatorgroup.yaml` file:

   ```yaml
   apiVersion: operators.coreos.com/v1
   kind: OperatorGroup
   metadata:
     generateName: openshift-special-resource-operator-
     name: openshift-special-resource-operator
     namespace: openshift-special-resource-operator
   spec:
     targetNamespaces:
     - openshift-special-resource-operator
   ```

   b. Create the operator group by running the following command:

   ```bash
   $ oc create -f sro-operatorgroup.yaml
   ```

   c. Create the following **Subscription** CR and save the YAML in the `sro-sub.yaml` file:

   **Example Subscription CR**

   ```yaml
   apiVersion: operators.coreos.com/v1alpha1
   kind: Subscription
   metadata:
     name: openshift-special-resource-operator
     namespace: openshift-special-resource-operator
   spec:
     channel: "stable"
     installPlanApproval: Automatic
     name: openshift-special-resource-operator
     source: redhat-operators
     sourceNamespace: openshift-marketplace
   ```

   d. Create the subscription object by running the following command:

   ```bash
   $ oc create -f sro-sub.yaml
   ```
e. Switch to the `openshift-special-resource-operator` project:

```
$ oc project openshift-special-resource-operator
```

Verification

- To verify that the Operator deployment is successful, run:

```
$ oc get pods
```

**Example output**

```
NAME                                                   READY   STATUS    RESTARTS   AGE
nfd-controller-manager-7f4c5f5778-4lvvk                2/2     Running   0          89s
special-resource-controller-manager-6dbf7d4f6f-9k18h   2/2     Running   0          81s
```

A successful deployment shows a **Running** status.

### 3.2.2. Installing the Special Resource Operator by using the web console

As a cluster administrator, you can install the Special Resource Operator (SRO) by using the OpenShift Container Platform web console.

**Prerequisites**

- You installed the Node Feature Discovery (NFD) Operator.

**Procedure**

1. Log in to the OpenShift Container Platform web console.

2. Create the required namespace for the Special Resource Operator:
   - Navigate to Administration → Namespaces and click Create Namespace.
   - Enter `openshift-special-resource-operator` in the Name field and click Create.

3. Install the Special Resource Operator:
   - In the OpenShift Container Platform web console, click Operators → OperatorHub.
   - Choose Special Resource Operator from the list of available Operators, and then click Install.
   - On the Install Operator page, select a specific namespace on the cluster select the namespace created in the previous section, and then click Install.

**Verification**

To verify that the Special Resource Operator installed successfully:

1. Navigate to the Operators → Installed Operators page.

2. Ensure that Special Resource Operator is listed in the `openshift-special-resource-operator` project with a Status of InstallSucceeded.
3. If the Operator does not appear as installed, to troubleshoot further:
   a. Navigate to the Operators → Installed Operators page and inspect the Operator Subscriptions and Install Plans tabs for any failure or errors under Status.
   b. Navigate to the Workloads → Pods page and check the logs for pods in the openshift-special-resource-operator project.

### 3.3. USING THE SPECIAL RESOURCE OPERATOR

The Special Resource Operator (SRO) is used to manage the build and deployment of a driver container. The objects required to build and deploy the container can be defined in a Helm chart.

The example in this section uses the simple-kmod SpecialResource object to point to a ConfigMap object that is created to store the Helm charts.

#### 3.3.1. Building and running the simple-kmod SpecialResource by using a config map

In this example, the simple-kmod kernel module shows how the Special Resource Operator (SRO) manages a driver container. The container is defined in the Helm chart templates that are stored in a config map.

**Prerequisites**

- You have a running OpenShift Container Platform cluster.
- You set the Image Registry Operator state to Managed for your cluster.
- You installed the OpenShift CLI (oc).
- You are logged into the OpenShift CLI as a user with cluster-admin privileges.
- You installed the Node Feature Discovery (NFD) Operator.
- You installed the SRO.
- You installed the Helm CLI (helm).

**Procedure**
1. To create a simple-kmod SpecialResource object, define an image stream and build config to build the image, and a service account, role, role binding, and daemon set to run the container. The service account, role, and role binding are required to run the daemon set with the privileged security context so that the kernel module can be loaded.

   a. Create a templates directory, and change into it:

   ```bash
   $ mkdir -p chart/simple-kmod-0.0.1/templates
   $ cd chart/simple-kmod-0.0.1/templates
   ```

   b. Save this YAML template for the image stream and build config in the templates directory as **0000-buildconfig.yaml**:

   ```yaml
   apiVersion: image.openshift.io/v1
   kind: ImageStream
   metadata:
     labels:
       app: {{.Values.specialresource.metadata.name}}-{{.Values.groupName.driverContainer}}
       name: {{.Values.specialresource.metadata.name}}-{{.Values.groupName.driverContainer}}
       spec: {}
   ---
   apiVersion: build.openshift.io/v1
   kind: BuildConfig
   metadata:
     labels:
       app: {{.Values.specialresource.metadata.name}}-{{.Values.groupName.driverBuild}}
       name: {{.Values.specialresource.metadata.name}}-{{.Values.groupName.driverBuild}}
     annotations:
       specialresource.openshift.io/wait: "true"
       specialresource.openshift.io/driver-container-vendor: simple-kmod
       specialresource.openshift.io/kernel-affine: "true"
   spec:
     nodeSelector:
       node-role.kubernetes.io/worker: ""
     runPolicy: "Serial"
     triggers:
     - type: "ConfigChange"
     - type: "ImageChange"
     source:
       git:
         ref: {{.Values.specialresource.spec.driverContainer.source.git.ref}}
         uri: {{.Values.specialresource.spec.driverContainer.source.git.uri}}
         type: Git
     strategy:
       dockerStrategy:
         dockerfilePath: Dockerfile.SRO
     buildArgs:
     - name: "IMAGE"
       value: {{ .Values.driverToolkitImage }}
       #{- range $arg := .Values.buildArgs }
   ```
The templates such as `{{.Values.specialresource.metadata.name}}` are filled in by the SRO, based on fields in the `SpecialResource` CR and variables known to the Operator such as `{{.Values.KernelFullVersion}}`.

c. Save the following YAML template for the RBAC resources and daemon set in the `templates` directory as `1000-driver-container.yaml`:
Change into the `chart/simple-kmod-0.0.1` directory:
e. Save the following YAML for the chart as Chart.yaml in the chart/simple-kmod-0.0.1 directory:

```yaml
apiVersion: v2
name: simple-kmod
description: Simple kmod will deploy a simple kmod driver-container
icon: https://avatars.githubusercontent.com/u/55542927
type: application
version: 0.0.1
appVersion: 1.0.0
```

2. From the chart directory, create the chart using the helm package command:

```bash
$ helm package simple-kmod-0.0.1/
```

Example output

Successfully packaged chart and saved it to:
```
/data/<username>/git/<github_username>/special-resource-operator/yaml-for-docs/chart/simple-kmod-0.0.1/simple-kmod-0.0.1.tgz
```

3. Create a config map to store the chart files:

a. Create a directory for the config map files:

```bash
$ mkdir cm
```

b. Copy the Helm chart into the cm directory:

```bash
$ cp simple-kmod-0.0.1.tgz cm/simple-kmod-0.0.1.tgz
```

c. Create an index file specifying the Helm repo that contains the Helm chart:

```bash
$ helm repo index cm --url=cm://simple-kmod/simple-kmod-chart
```

d. Create a namespace for the objects defined in the Helm chart:

```bash
$ oc create namespace simple-kmod
```

e. Create the config map object:

```bash
$ oc create cm simple-kmod-chart --from-file=cm/index.yaml --from-file=cm/simple-kmod-0.0.1.tgz -n simple-kmod
```

4. Use the following SpecialResource manifest to deploy the simple-kmod object using the Helm chart that you created in the config map. Save this YAML as simple-kmod-configmap.yaml:

```yaml
apiVersion: sro.openshift.io/v1beta1
kind: SpecialResource
metadata:
```

name: simple-kmod
spec:
    #debug: true
namespace: simple-kmod
chart:
    name: simple-kmod
    version: 0.0.1
    repository:
        name: example
        url: cm://simple-kmod/simple-kmod-chart
set:
    kind: Values
    apiVersion: sro.openshift.io/v1beta1
    kmodNames:
      - simple-kmod
      - simple-procfs-kmod
    buildArgs:
      - name: KMODVER
        value: "SRO"
    driverContainer:
        source:
            git:
                ref: "master"
                url: "https://github.com/openshift-psap/kvc-simple-kmod.git"

Optional: Uncomment the #debug: true line to have the YAML files in the chart printed in full in the Operator logs and to verify that the logs are created and templated properly.

The spec.chart.repository.url field tells the SRO to look for the chart in a config map.

5. From a command line, create the SpecialResource file:

   $ oc create -f simple-kmod-configmap.yaml

   NOTE
   To remove the simple-kmod kernel module from the node, delete the simple-kmod SpecialResource API object using the oc delete command. The kernel module is unloaded when the driver container pod is deleted.

Verification

The simple-kmod resources are deployed in the simple-kmod namespace as specified in the object manifest. After a short time, the build pod for the simple-kmod driver container starts running. The build completes after a few minutes, and then the driver container pods start running.

1. Use oc get pods command to display the status of the build pods:

   $ oc get pods -n simple-kmod

   Example output

<table>
<thead>
<tr>
<th>NAME</th>
<th>READY</th>
<th>STATUS</th>
<th>RESTARTS</th>
<th>AGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple-kmod-driver-build-12813789169ac0ee-1-build</td>
<td>0/1</td>
<td>Completed</td>
<td>0</td>
<td>7m12s</td>
</tr>
<tr>
<td>simple-kmod-driver-container-12813789169ac0ee-mjsnh</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>8m2s</td>
</tr>
</tbody>
</table>
2. Use the `oc logs` command, along with the build pod name obtained from the `oc get pods` command above, to display the logs of the simple-kmod driver container image build:

```
$ oc logs pod/simple-kmod-driver-build-12813789169ac0ee-1-build -n simple-kmod
```

3. To verify that the simple-kmod kernel modules are loaded, execute the `lsmod` command in one of the driver container pods that was returned from the `oc get pods` command above:

```
$ oc exec -n simple-kmod -it pod/simple-kmod-driver-container-12813789169ac0ee-mjsnh -- lsmod | grep simple
```

**Example output**

<table>
<thead>
<tr>
<th>Module</th>
<th>Size</th>
<th>Count</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple_procfs_kmod</td>
<td>16384</td>
<td>0</td>
</tr>
<tr>
<td>simple_kmod</td>
<td>16384</td>
<td>0</td>
</tr>
</tbody>
</table>

**TIP**

The `sro_kind_completed_info` SRO Prometheus metric provides information about the status of the different objects being deployed, which can be useful to troubleshoot SRO CR installations. The SRO also provides other types of metrics that you can use to watch the health of your environment.

### 3.4. PROMETHEUS SPECIAL RESOURCE OPERATOR METRICS

The Special Resource Operator (SRO) exposes the following Prometheus metrics through the `metrics` service:

<table>
<thead>
<tr>
<th>Metric Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>sro_used_nodes</code></td>
<td>Returns the nodes that are running pods created by a SRO custom resource (CR). This metric is available for <code>DaemonSet</code> and <code>Deployment</code> objects only.</td>
</tr>
<tr>
<td><code>sro_kind_completed_info</code></td>
<td>Represents whether a kind of an object defined by the Helm Charts in a SRO CR has been successfully uploaded in the cluster (value \textbf{1}) or not (value \textbf{0}). Examples of objects are <code>DaemonSet</code>, <code>Deployment</code> or <code>BuildConfig</code>.</td>
</tr>
<tr>
<td><code>sro_states_completed_info</code></td>
<td>Represents whether the SRO has finished processing a CR successfully (value \textbf{1}) or the SRO has not processed the CR yet (value \textbf{0}).</td>
</tr>
<tr>
<td><code>sro_managed_resources_total</code></td>
<td>Returns the number of SRO CRs in the cluster, regardless of their state.</td>
</tr>
</tbody>
</table>

### 3.5. ADDITIONAL RESOURCES
- For information about restoring the Image Registry Operator state before using the Special Resource Operator, see *Image registry removed during installation*.
- For details about installing the NFD Operator see *Node Feature Discovery (NFD) Operator*.
CHAPTER 4. NODE FEATURE DISCOVERY OPERATOR

Learn about the Node Feature Discovery (NFD) Operator and how you can use it to expose node-level information by orchestrating Node Feature Discovery, a Kubernetes add-on for detecting hardware features and system configuration.

4.1. ABOUT THE NODE FEATURE DISCOVERY OPERATOR

The Node Feature Discovery Operator (NFD) manages the detection of hardware features and configuration in an OpenShift Container Platform cluster by labeling the nodes with hardware-specific information. NFD labels the host with node-specific attributes, such as PCI cards, kernel, operating system version, and so on.

The NFD Operator can be found on the Operator Hub by searching for “Node Feature Discovery”.

4.2. INSTALLING THE NODE FEATURE DISCOVERY OPERATOR

The Node Feature Discovery (NFD) Operator orchestrates all resources needed to run the NFD daemon set. As a cluster administrator, you can install the NFD Operator by using the OpenShift Container Platform CLI or the web console.

4.2.1. Installing the NFD Operator using the CLI

As a cluster administrator, you can install the NFD Operator using the CLI.

Prerequisites

- An OpenShift Container Platform cluster
- Install the OpenShift CLI (oc).
- Log in as a user with cluster-admin privileges.

Procedure

1. Create a namespace for the NFD Operator.
   
   a. Create the following Namespace custom resource (CR) that defines the openshift-nfd namespace, and then save the YAML in the nfd-namespace.yaml file:

   ```yaml
   apiVersion: v1
   kind: Namespace
   metadata:
     name: openshift-nfd
   
   $ oc create -f nfd-namespace.yaml
   ```

   b. Create the namespace by running the following command:

   ```bash
   $ oc create -f nfd-namespace.yaml
   ```

2. Install the NFD Operator in the namespace you created in the previous step by creating the following objects:

   a. Create the following OperatorGroup CR and save the YAML in the nfd-operatorgroup.yaml file:
b. Create the **OperatorGroup** CR by running the following command:

```
$ oc create -f nfd-operatorgroup.yaml
```

c. Create the following **Subscription** CR and save the YAML in the **nfd-sub.yaml** file:

```
Example Subscription
```

```
apiVersion: operators.coreos.com/v1alpha1
kind: Subscription
metadata:
  name: nfd
  namespace: openshift-nfd
spec:
  channel: "stable"
  installPlanApproval: Automatic
  name: nfd
  source:
    repository: https://mirror.openshift.com/pub/openshift-source-redhat
    sourceNamespace: openshift-marketplace
```

d. Create the subscription object by running the following command:

```
$ oc create -f nfd-sub.yaml
```

e. Change to the **openshift-nfd** project:

```
$ oc project openshift-nfd
```

**Verification**

- To verify that the Operator deployment is successful, run:

```
$ oc get pods
```

**Example output**

<table>
<thead>
<tr>
<th>NAME</th>
<th>READY</th>
<th>STATUS</th>
<th>RESTARTS</th>
<th>AGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>nfd-controller-manager-7f86ccfb58-vgr4x</td>
<td>2/2</td>
<td>Running</td>
<td>0</td>
<td>10m</td>
</tr>
</tbody>
</table>

A successful deployment shows a **Running** status.

---

4.2.2. Installing the NFD Operator using the web console
As a cluster administrator, you can install the NFD Operator using the web console.

Procedure

1. In the OpenShift Container Platform web console, click **Operators → OperatorHub**.
2. Choose **Node Feature Discovery** from the list of available Operators, and then click **Install**.
3. On the **Install Operator** page, select **A specific namespace on the cluster** and then click **Install**. You do not need to create a namespace because it is created for you.

Verification

To verify that the NFD Operator installed successfully:

1. Navigate to the **Operators → Installed Operators** page.
2. Ensure that **Node Feature Discovery** is listed in the **openshift-nfd** project with a **Status** of **InstallSucceeded**.

**NOTE**

During installation an Operator might display a **Failed** status. If the installation later succeeds with an **InstallSucceeded** message, you can ignore the **Failed** message.

Troubleshooting

If the Operator does not appear as installed, troubleshoot further:

1. Navigate to the **Operators → Installed Operators** page and inspect the **Operator Subscriptions** and **Install Plans** tabs for any failure or errors under **Status**.
2. Navigate to the **Workloads → Pods** page and check the logs for pods in the **openshift-nfd** project.

4.3. USING THE NODE FEATURE DISCOVERY OPERATOR

The Node Feature Discovery (NFD) Operator orchestrates all resources needed to run the Node-Feature-Discovery daemon set by watching for a **NodeFeatureDiscovery** CR. Based on the **NodeFeatureDiscovery** CR, the Operator will create the operand (NFD) components in the desired namespace. You can edit the CR to choose another **namespace**, **image**, **imagePullPolicy**, and **nfd-worker-conf**, among other options.

As a cluster administrator, you can create a **NodeFeatureDiscovery** instance using the OpenShift Container Platform CLI or the web console.

4.3.1. Create a NodeFeatureDiscovery instance using the CLI

As a cluster administrator, you can create a **NodeFeatureDiscovery** CR instance using the CLI.

Prerequisites

- An OpenShift Container Platform cluster
- Install the OpenShift CLI (oc).
- Log in as a user with cluster-admin privileges.
- Install the NFD Operator.

Procedure

1. Create the following NodeFeatureDiscovery Custom Resource (CR), and then save the YAML in the NodeFeatureDiscovery.yaml file:

```yaml
apiVersion: nfd.openshift.io/v1
customResourceDefinition:
  name: nfd-instance
spec:
  instance: "" # instance is empty by default
topologyupdater: false # False by default
operand:
  imagePullPolicy: Always
workerConfig:
  configData: |
    core:
      # labelWhiteList:
      # noPublish: false
      # sleepInterval: 60s
      # sources: [all]
      # klog:
      #   addDirHeader: false
      #   alsoLogToStderr: false
      #   logBacktraceAt:
      #   logToFile: true
      #   skipHeaders: false
      #   stderrThreshold: 2
      #   v: 0
      #   vmodule:
      ## NOTE: the following options are not dynamically run-time configurable
      ## and require a nfd-worker restart to take effect after being changed
      #   logDir:
      #   logFile:
      #   logFileMaxSize: 1800
      #   skipLogHeaders: false
    sources:
    cpu:
    cpuId:
      # NOTE: whitelist has priority over blacklist
      attributeBlacklist:
        - "BMI1"
        - "BMI2"
        - "CLMUL"
        - "CMOV"
        - "CX16"
        - "ERMS"
        - "F16C"
        - "HTT"
```
For more details on how to customize NFD workers, refer to the Configuration file reference of nfd-worker.

1. Create the NodeFeatureDiscovery CR instance by running the following command:

   ```bash
   $ oc create -f NodeFeatureDiscovery.yaml
   ```

**Verification**

- To verify that the instance is created, run:

  ```bash
  $ oc get pods
  ```

**Example output**

<table>
<thead>
<tr>
<th>NAME</th>
<th>READY</th>
<th>STATUS</th>
<th>RESTARTS</th>
<th>AGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>nfd-controller-manager-7f86ccfb58-vgr4x</td>
<td>2/2</td>
<td>Running</td>
<td>0</td>
<td>11m</td>
</tr>
<tr>
<td>nfd-master-hcn64</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>60s</td>
</tr>
<tr>
<td>nfd-master-lnnxx</td>
<td>1/1</td>
<td>Running</td>
<td>0</td>
<td>60s</td>
</tr>
</tbody>
</table>
A successful deployment shows a **Running** status.

### 4.3.2. Create a NodeFeatureDiscovery CR using the web console

**Procedure**

1. Navigate to the **Operators → Installed Operators** page.
2. Find **Node Feature Discovery** and see a box under **Provided APIs**.
3. Click **Create instance**.
4. Edit the values of the **NodeFeatureDiscovery** CR.
5. Click **Create**.

### 4.4. CONFIGURING THE NODE FEATURE DISCOVERY OPERATOR

#### 4.4.1. core

The **core** section contains common configuration settings that are not specific to any particular feature source.

**core.sleepInterval**

**core.sleepInterval** specifies the interval between consecutive passes of feature detection or re-detection, and thus also the interval between node re-labeling. A non-positive value implies infinite sleep interval; no re-detection or re-labeling is done.

This value is overridden by the deprecated **--sleep-interval** command line flag, if specified.

**Example usage**

```yaml
core:
  sleepInterval: 60s
```

The default value is **60s**.

**core.sources**

**core.sources** specifies the list of enabled feature sources. A special value **all** enables all feature sources.

This value is overridden by the deprecated **--sources** command line flag, if specified.

Default: **[all]**

**Example usage**

```yaml
core:
  sources:
    - system
```
core.labelWhiteList
core.labelWhiteList specifies a regular expression for filtering feature labels based on the label name. Non-matching labels are not published.

The regular expression is only matched against the basename part of the label, the part of the name after ‘/’. The label prefix, or namespace, is omitted.

This value is overridden by the deprecated --label-whitelist command line flag, if specified.

Default: null

Example usage

core:
  labelWhiteList: "^cpu-cpuid"

core.noPublish
Setting core.noPublish to true disables all communication with the nfd-master. It is effectively a dry run flag; nfd-worker runs feature detection normally, but no labeling requests are sent to nfd-master.

This value is overridden by the --no-publish command line flag, if specified.

Example:

Example usage

core:
  noPublish: true

The default value is false.

core.klog
The following options specify the logger configuration, most of which can be dynamically adjusted at run-time.

The logger options can also be specified using command line flags, which take precedence over any corresponding config file options.

core.klog.addDirHeader
If set to true, core.klog.addDirHeader adds the file directory to the header of the log messages.

Default: false

Run-time configurable: yes

core.klog.alsologtostderr
Log to standard error as well as files.

Default: false

Run-time configurable: yes

core.klog.logBacktraceAt
When logging hits line file:N, emit a stack trace.
Default: **empty**

Run-time configurable: yes

**core.klog.logDir**
If non-empty, write log files in this directory.

Default: **empty**

Run-time configurable: no

**core.klog.logFile**
If not empty, use this log file.

Default: **empty**

Run-time configurable: no

**core.klog.logFileMaxSize**
**core.klog.logFileMaxSize** defines the maximum size a log file can grow to. Unit is megabytes. If the value is **0**, the maximum file size is unlimited.

Default: **1800**

Run-time configurable: no

**core.klog.logtostderr**
Log to standard error instead of files

Default: **true**

Run-time configurable: yes

**core.klog.skipHeaders**
If **core.klog.skipHeaders** is set to **true**, avoid header prefixes in the log messages.

Default: **false**

Run-time configurable: yes

**core.klog.skipLogHeaders**
If **core.klog.skipLogHeaders** is set to **true**, avoid headers when opening log files.

Default: **false**

Run-time configurable: no

**core.klog.stderrthreshold**
Logs at or above this threshold go to stderr.

Default: **2**

Run-time configurable: yes

**core.klog.v**
**core.klog.v** is the number for the log level verbosity.

Default: **0**
Run-time configurable: yes

core.klog.vmodule  
core.klog.vmodule is a comma-separated list of \texttt{pattern=N} settings for file-filtered logging.

Default: empty

Run-time configurable: yes

4.4.2. sources

The \texttt{sources} section contains feature source specific configuration parameters.

\texttt{sources.cpu.cpuid.attributeBlacklist}  
Prevent publishing \texttt{cpuid} features listed in this option.

This value is overridden by \texttt{sources.cpu.cpuid.attributeWhitelist}, if specified.

Default: [\texttt{BMI1}, \texttt{BMI2}, \texttt{CLMUL}, \texttt{CMOV}, \texttt{CX16}, \texttt{ERMS}, \texttt{F16C}, \texttt{HTT}, \texttt{LZCNT}, \texttt{MMX}, \texttt{MMXEXT}, \texttt{NX}, \texttt{POPCNT}, \texttt{RDRAND}, \texttt{RDSEED}, \texttt{RDTSCP}, \texttt{SGX}, \texttt{SGXLC}, \texttt{SSE}, \texttt{SSE2}, \texttt{SSE3}, \texttt{SSE4.1}, \texttt{SSE4.2}, \texttt{SSSE3}]

Example usage

```
sources:  
  cpu:  
    cpuid:  
      attributeBlacklist: [MMX, MMXEXT]
```

\texttt{sources.cpu.cpuid.attributeWhitelist}  
Only publish the \texttt{cpuid} features listed in this option.

\texttt{sources.cpu.cpuid.attributeWhitelist} takes precedence over \texttt{sources.cpu.cpuid.attributeBlacklist}.

Default: empty

Example usage

```
sources:  
  cpu:  
    cpuid:  
      attributeWhitelist: [AVX512BW, AVX512CD, AVX512DQ, AVX512F, AVX512VL]
```

\texttt{sources.kernel.kconfigFile}  
\texttt{sources.kernel.kconfigFile} is the path of the kernel config file. If empty, NFD runs a search in the well-known standard locations.

Default: empty

Example usage

```
sources:  
  kernel:  
    kconfigFile: "/path/to/kconfig"
```

\texttt{sources.kernel.configOpts}
sources.kernel.configOpts represents kernel configuration options to publish as feature labels.

Default: [NO_HZ, NO_HZ_IDLE, NO_HZ_FULL, PREEMPT]

Example usage

```yaml
sources:
  kernel:
    configOpts: [NO_HZ, X86, DMI]
```

sources.pci.deviceClassWhitelist

sources.pci.deviceClassWhitelist is a list of PCI device class IDs for which to publish a label. It can be specified as a main class only (for example, 03) or full class-subclass combination (for example 0300). The former implies that all subclasses are accepted. The format of the labels can be further configured with deviceLabelFields.

Default: ["03", "0b40", "12"]

Example usage

```yaml
sources:
  pci:
    deviceClassWhitelist: ["0200", "03"]
```

sources.pci.deviceLabelFields

sources.pci.deviceLabelFields is the set of PCI ID fields to use when constructing the name of the feature label. Valid fields are class, vendor, device, subsystem_vendor and subsystem_device.

Default: [class, vendor]

Example usage

```yaml
sources:
  pci:
    deviceLabelFields: [class, vendor, device]
```

With the example config above, NFD would publish labels such as feature.node.kubernetes.io/pci-class-id<_vendor-id>_device-id>.present=true

sources.usb.deviceClassWhitelist

sources.usb.deviceClassWhitelist is a list of USB device class IDs for which to publish a feature label. The format of the labels can be further configured with deviceLabelFields.

Default: ["0e", "ef", "fe", "ff"]

Example usage

```yaml
sources:
  usb:
    deviceClassWhitelist: ["ef", "ff"]
```

sources.usb.deviceLabelFields

sources.usb.deviceLabelFields is the set of USB ID fields from which to compose the name of the feature label. Valid fields are class, vendor, and device.
Default: `[class, vendor, device]`

Example usage

```
sources:
pci:
  deviceLabelFields: [class, vendor]
```

With the example config above, NFD would publish labels like: `feature.node.kubernetes.io/usb-<class-id>_<vendor-id>.present=true`.

**sources.custom**

`sources.custom` is the list of rules to process in the custom feature source to create user-specific labels.

Default: `empty`

Example usage

```
sources.custom
- name: "my.custom.feature"
  matchOn:
    - loadedKMod: ["e1000e"]
    - pciId:
      class: ["0200"]
      vendor: ["8086"]
```

### 4.5. USING THE NFD TOPOLOGY UPDATER

The Node Feature Discovery (NFD) Topology Updater is a daemon responsible for examining allocated resources on a worker node. It accounts for resources that are available to be allocated to new pod on a per-zone basis, where a zone can be a Non-Uniform Memory Access (NUMA) node. The NFD Topology Updater communicates the information to nfd-master, which creates a `NodeResourceTopology` custom resource (CR) corresponding to all of the worker nodes in the cluster. One instance of the NFD Topology Updater runs on each node of the cluster.

To enable the Topology Updater workers in NFD, set the `topologyupdater` variable to `true` in the `NodeFeatureDiscovery` CR, as described in the section **Using the Node Feature Discovery Operator**.

#### 4.5.1. NodeResourceTopology CR

When run with NFD Topology Updater, NFD creates custom resource instances corresponding to the node resource hardware topology, such as:

```
apiVersion: topology.node.k8s.io/v1alpha1
kind: NodeResourceTopology
metadata:
  name: node1
topologyPolicies: ["SingleNUMANodeContainerLevel"]
zones:
- name: node-0
type: Node
resources:
```

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4.5.2. NFD Topology Updater command line flags

To view available command line flags, run the `nfd-topology-updater -help` command. For example, in a podman container, run the following command:

```
$ podman run gcr.io/k8s-staging-nfd/node-feature-discovery:master nfd-topology-updater -help
```

- `ca-file`

The `-ca-file` flag is one of the three flags, together with the `-cert-file` and `-key-file` flags, that controls the mutual TLS authentication on the NFD Topology Updater. This flag specifies the TLS root certificate that is used for verifying the authenticity of nfd-master.

Default: empty

**IMPORTANT**

The `-ca-file` flag must be specified together with the `-cert-file` and `-key-file` flags.

**Example**

```
$ nfd-topology-updater -ca-file=/opt/nfd/ca.crt -cert-file=/opt/nfd/updater.crt -key-file=/opt/nfd/updater.key
```
The **-cert-file** flag is one of the three flags, together with the **-ca-file** and **-key-file** flags, that controls mutual TLS authentication on the NFD Topology Updater. This flag specifies the TLS certificate presented for authenticating outgoing requests.

Default: empty

### IMPORTANT

The **-cert-file** flag must be specified together with the **-ca-file** and **-key-file** flags.

### Example

```
$ nfd-topology-updater -cert-file=/opt/nfd/updater.crt -key-file=/opt/nfd/updater.key -ca-file=/opt/nfd/ca.crt
```

---

The **-key-file** flag is one of the three flags, together with the **-ca-file** and **-cert-file** flags, that controls the mutual TLS authentication on the NFD Topology Updater. This flag specifies the private key corresponding the given certificate file, or **-cert-file**, that is used for authenticating outgoing requests.

Default: empty

### IMPORTANT

The **-key-file** flag must be specified together with the **-ca-file** and **-cert-file** flags.

### Example

```
$ nfd-topology-updater -key-file=/opt/nfd/updater.key -cert-file=/opt/nfd/updater.crt -ca-file=/opt/nfd/ca.crt
```

---

The **-kubelet-config-file** specifies the path to the Kubelet’s configuration file.

Default: `/host-var/lib/kubelet/config.yaml`

### Example

```
$ nfd-topology-updater -kubelet-config-file=/var/lib/kubelet/config.yaml
```

---

The **-no-publish** flag disables all communication with the nfd-master, making it a dry run flag for nfd-topology-updater. NFD Topology Updater runs resource hardware topology detection normally, but no CR requests are sent to nfd-master.

Default: `false`

### Example
4.5.2.1. -oneshot

The -oneshot flag causes the NFD Topology Updater to exit after one pass of resource hardware topology detection.

Default: false

Example

$ nfd-topology-updater -oneshot

-podresources-socket

The -podresources-socket flag specifies the path to the Unix socket where kubelet exports a gRPC service to enable discovery of in-use CPUs and devices, and to provide metadata for them.

Default: /host-var/lib/lib/kubelet/pod-resources/kubelet.sock

Example

$ nfd-topology-updater -podresources-socket=/var/lib/kubelet/pod-resources/kubelet.sock

-server

The -server flag specifies the address of the nfd-master endpoint to connect to.

Default: localhost:8080

Example

$ nfd-topology-updater -server=localhost:443

-server-name-override

The -server-name-override flag specifies the common name (CN) which to expect from the nfd-master TLS certificate. This flag is mostly intended for development and debugging purposes.

Default: empty

Example

$ nfd-topology-updater -server-name-override=localhost

-sleep-interval

The -sleep-interval flag specifies the interval between resource hardware topology re-examination and custom resource updates. A non-positive value implies infinite sleep interval and no re-detection is done.

Default: 60s

Example

$ nfd-topology-updater -sleep-interval=1h
-version
Print version and exit.

-watch-namespace
The **-watch-namespace** flag specifies the namespace to ensure that resource hardware topology examination only happens for the pods running in the specified namespace. Pods that are not running in the specified namespace are not considered during resource accounting. This is particularly useful for testing and debugging purposes. A * value means that all of the pods across all namespaces are considered during the accounting process.

Default: *

Example

```
$ nfd-topology-updater -watch-namespace=rte
```